

Software Verification and Validation

White-box testing. Test coverage

12 October 2016

White-box Testing

Tests are generated based on *internal structure* of code

Other (better) names: glass box, clear box, open box

Another classification:

behavioral testing (black-box) / *structural* (white-box)

Comparison:

- black-box: at any level / white-box: mostly module/unit testing
- white-box: code change \Rightarrow tests change
- white-box: easier detection of *coding errors*,
but cannot detect *omission errors* (in code or spec)

Program structure: Terminology

Control flow graph (CFG)

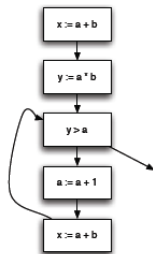
graph representation of program
and implicitly its execution paths

nodes = instructions

edges (labeled w. conditions):

sequencing between instructions

```
x := a + b;  
y := a * b;  
while (y > a) {  
  a := a + 1;  
  x := a + b  
}
```



Usually, straight-line code is grouped together \Rightarrow

basic block =

a sequence of statements with just one entry and one exit point
(no jumps into middle of code, or from code outside)

Code coverage

= a criterion to measure if a set of tests is *adequate*

What good are such criteria ? For questions as:

What program properties should we examine ?

What test data do we select for such properties ?

What *quantitative* objectives do we set for testing ?

Did we test enough ?

The impossible ideal: test all program executions

⇒ i.e., *all paths* through the CFG

But: number of program paths usually infinite (loops, recursion)
also: one path, multiple data (proper equivalence classes?)

⇒ must choose modest structural criteria

⇒ but not arbitrary – chosen *judiciously*

Testing axioms (Weyuker)

Antiextensionality:

There are equivalent programs P și Q such that a test suite T is adequate for P but not for Q .

i.e. *semantically* equivalent programs may need different test suites

General Multiple Change:

There are programs P and Q that have the same form (structure) and a test suite T which is adequate for P but not for Q .

i.e. *syntactically* close programs may need different test suites

Criteria: Line coverage

also: statement coverage, basic block coverage

Sufficient tests to execute each program statement

Obviously a necessary criterion (not executed = not tested)

obviously also insufficient

```
char a[5], *s = NULL;  
if (len < 5)  
    s = a;  
*s = 't';
```

Test with `len = 4` covers all statements; misses error

Branch coverage

also: decision coverage

Tests every possible value of a decision (true/false)

more precise definition: also tests every entry and exit from program

usually implies statement coverage

(every instruction is on some branch; see exception below)

The following are also decisions / branches

switch/case statements (multiple branches)

exception handling (hard to test, often neglected)

every *potential* exception is a branching point

code that looks straight-line in reality isn't

Caution: functions or side-effects in decisions:

if (a && (b || f(x, y)))

does not call f if a and b both true

⇒ a case where branch coverage does not subsume line coverage

Condition coverage

A *condition* is an *elementary boolean expression* in a *decision*
needs tests for each possible value of a condition
apparently more complex than decision coverage, but does not
subsume it

Example

```
if (x > 5 && y == 3) /*some code */
```

Two tests: $x = 6, y = 2$ and $x = 4, y = 3$
generate all possible condition values (T and F, F and T)
but follow the same branch (false)

Condition/decision coverage

Simultaneously covers *both* criteria

May need more tests than individual methods or just recombining them

Example

```
if (x > 5 && y == 3) /*some code */
```

two tests are still enough: $x = 6, y = 3$, and $x = 4, y = 2$

May be insufficient: the effect of some conditions may *mask* others

Multiple condition coverage

Tests all combinations for the *subexpressions* (conditions) of the decision

Exponential in number of conditions (2^n tests for n conditions)

⇒ often too expensive to implement

In practice, some of the 2^n combinations

– may be irrelevant (for short-circuit evaluation)

– may be infeasible (when conditions are not independent)

⇒ in general, this requirement is not justified

Modified Condition/Decision Coverage

One of the strongest criteria; initially developed at Boeing
is a requirement in avionics/safety-critical systems (standard DO-178B)

Complete requirements for an MC/DC test suite:

- All program entry and exit points covered

- Each decision exercised on both branches

- Each condition takes both values

- Each condition is shown to affect its enclosing decision
(keep other conditions fixed, varying condition of interest)*

Same tests, whether language has short-circuit evaluation or not.

Constructing an MC/DC test suite

Start from base cases $\&\&$ and $\|\|$ with two conditions

AND operator $\&\&$ has a single case (t t) with result t.

Changing any condition to f, result becomes f.

Likewise for $\|\|$ (dual operator), switching t and f.

a	b	a && b			a	b	a b		
f	t	f	(1)	a: (1, 3)	t	f	t	(1)	
t	f	f	(2)		b: (2, 3)	f	t	t	(2)
t	t	t	(3)			f	f	f	(3)

We indicate the pair of tests relevant for each condition:

(1, 3) shows a may influence decision; likewise, (2, 3) for b.

For n conditions: a test with all the same, n tests with one each flipped

a	b	c	a && b && c		
f	t	t	f	(1)	a: (1, 4) b: (2, 4) c: (3, 4)
t	f	t	f	(2)	
t	t	f	f	(3)	
t	t	t	t	(4)	

MC/DC Construction Example

Consider $a \ \&\& \ b \ \&\& \ (c \ || \ d \ \&\& \ e)$

Start from innermost expression(s), $d \ \&\& \ e$ (watch precedence!)

d	e	d && e		
f	t	f	(1)	d: (1, 3) e: (2, 3)
t	f	f	(2)	
t	t	t	(3)	

We then add $c \ ||$.

Since $||$ with f does not change truth, add $c=f$ to all tests (1-3).

For the new test (4), choose test with f result (2) and add $c=t$.

c	d	e	c d && e		
f	f	t	f	(1)	Now also shows effect of c: c: (2, 4) d: (1, 3) e: (2, 3)
f	t	f	f	(2)	
f	t	t	t	(3)	
t	t	f	t	(4)	

MC/DC example (cont.)

Now add a $\&\&$ b $\&\&$. To previous tests, add a=t, b=t.

Then choose a test with t result (4), flip in turn a and b to f, showing a and b influence decision:

a	b	c	d	e	a $\&\&$ b $\&\&$ (c d $\&\&$ e)		
t	t	f	f	t	f	(1)	
t	t	f	t	f	f	(2)	a: (4, 5)
t	t	f	t	t	t	(3)	b: (4, 6)
t	t	t	t	f	t	(4)	c: (2, 4)
f	t	t	t	f	f	(5)	d: (1, 3)
t	f	t	t	f	f	(6)	e: (2, 3)

Each test pair has one condition shown to influence outcome, all other conditions have the same value in both tests.

By construction, it follows that n variables need $n + 1$ tests.

MC/DC coverage: example 2

Consider $a \ \&\& \ b \ || \ c \ \&\& \ d$.

We write tests for both subexpressions (given by precedence)

a	b	a && b	a: (1', 3')	c	d	c && d	
f	t	f	(1')	f	t	f	(1'')
t	f	f	(2')	t	f	f	(2'')
t	t	t	(3')	t	t	t	(3'')

We combine with $||$. Since $||$ with f has no effect, choose one f test from each group ($1' + 1''$) and combine with all tests in the other group.

a	b	c	d	a && b c && d	
f	t	f	t	f	(1=1'+1'') a: (1, 5)
f	t	t	f	f	(2=1'+2'') b: (4, 5)
f	t	t	t	t	(3=1'+3'') c: (1, 3)
t	f	f	t	f	(4=2'+1'') d: (2, 3)
t	t	f	t	t	(5=3'+1'')

We have thus kept the influence of each individual condition.

MC/DC in real code

The above analysis is valid for *independent conditions*

it's always possible to generate the designed tests

In reality, conditions may be *coupled* (correlated)

Example: $(z - x \geq 3 \ \&\& \ z - y \geq 1 \ || \ y < 5) \ \&\& \ x \leq 3$

To have $z - x \geq 3$ influence the condition, we'd need

$x \leq 3$, and $y \geq 5$, and $z - y \geq 1$

But from these, we get $z - x \geq 3$, thus the condition can't be false, and can't influence the decision!

⇒ trying to get MC/DC coverage, we can detect if a condition is written needlessly complex, or has irrelevant parts (a possible logic error)

In this case, since $z - x < 3$ can't have an effect, the condition can be rewritten setting $z - x \geq 3$ to *true*:

$$(z - y \geq 1 \ || \ y < 5) \ \&\& \ x \leq 3$$

Unique-Cause MC/DC vs. Masking MC/DC

Unique-Cause MC/DC

the initially presented variant: the influence of a condition must be shown keeping all other conditions unchanged

may be impossible to achieve for coupled conditions

Masking MC/DC

a relaxed variant:

in the test pair, not all conditions must have same value,
but both combinations must show the effect of the scrutinized condition

In practice: combination

unique cause for all independent conditions

masking MC/DC for coupled conditions

Predicate coverage

or predicate-complete coverage [T. Ball, 2004]

Previous criteria do NOT correlate multiple decisions

⇒ e.g. combinations of successive `if` statements in the program

⇒ we need a criterion closer to *path coverage*
(which would cover all execution paths)

Approach: identify n relevant *predicates* (conditions) in the program

Try to generate all $S \cdot 2^n$ possible combinations

S states (program locations), n predicates

⇒ correlates between them all states and predicates in the program

Predicate coverage example [T. Ball]

```
void partition(int a[], int n) { // assume(n>2);
    int pivot = a[0];
    int lo = 1, hi = n-1;
    while (lo <= hi) {
        while (a[lo] <= pivot)
            lo++;
        while (a[hi] > pivot)
            hi--;
        if (lo < hi)
            swap(a,lo,hi);
    }
}
```

Is it correct? Do you detect an error?

Relevant predicates: branch conditions

$lo \leq hi$, $lo < hi$, $a[lo] \leq pivot$, $a[hi] > pivot$

Coverage criteria for cycles

[Beizer, Software Testing Techniques]

For simple cycles

- zero iterations (cycle is skipped)
 - possibly also: negative counter – correct behavior?
- one iteration
- two iterations (may catch *initialization errors*)
- one typical intermediate value
- N-1 iterations
- N iterations
- try to force N+1 iterations (more than assumed max)

For nonzero minimum: try min-1, min, min+1 ...

Coverage for multiple cycles [Beizer]

1. minimal number of outer iterations
try inner cycle completely (as independent cycle)
2. continue following cycles outwards
 - with inner cycle at typical iteration count
 - vary count for current cycle
3. finally, vary all cycles together from min to max

Other path testing criteria

Boundary interior path testing

- all paths that traverse a cycle once, without repetition
(boundary test)
- all paths that repeat a test, at most once
(interior test)

Linear Code Sequence and Jump (LCSAJ)

an LCSAJ sequence: straight line code followed by a jump

length N LCSAJ criterion: N such consecutive sequences

$N = 1$ ensures line coverage

$N = 2$ ensures branch coverage (even more)

Mutation-based testing

Try changing decisions/statements according to some patterns to detect if the program runs differently

Examples:

- $<$ changed to \leq , etc.
- $+1$ changed to -1 or ignored
- limits changed by ± 1
- $a \ || \ b$ changed to a , resp. b
(is the test relevant?); same for $a \ \&\& \ b$

If a mutation is not caught (“mutant not killed”) by any test

⇒ either tests are insufficient

⇒ or program may be wrong (or has irrelevant code)

Dataflow coverage criteria

Criteria so far: linked to program *control flow*

Alternative: criteria linked to *data flow* (*dataflow coverage*)

Key notions:

- variable *definition* (**def**): place where it's assigned
- variable **use**: place where it is read
(used in expression or tested in condition)

Various coverage criteria, e.g.: all-defs, all-uses

def-use coverage: cover each *feasible* pair of def-use with a test case

How relevant is coverage?

Errors increase with complexity

Cyclomatic complexity (of CFG)

= $E - V + 2$ (E = edges, V = nodes)

is a good measure for complexity

We want better coverage for more complex code

But: code coverage is not an absolute measure for test quality

cf. Brian Marick: How to misuse code coverage